

**RS 422 interface (TTL) incremental encoder**

<b>Product name</b>	<b>TTL (RS 422) incremental encoder</b>
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<b>Encoder operating voltage</b>	5 V DC $\pm 10\%$ or 10 ... 30 V DC
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<b>Sampling frequency, max.</b>	300 kHz
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<b>No-load current consumption, max.</b>	150 mA
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<b>Signal level</b>	TTL (RS 422)
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<b>Outputs protected against short-circuit to 0 V</b>	Yes
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<b>Switching time (10 ... 90%) (with 1 m (3.3 ft) cable and recommended input circuit)</b>	Rise/fall time $t_+/t_- \leq 50$ ns
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<b>Phase angle, signal A to B min. edge spacing at:</b>	90°
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- 300 kHz  $\geq 0.45$   $\mu$ s

<b>Cable length to electronic circuitry <sup>1)</sup>, max.</b>	100 m (328 ft)
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<b>LED failure monitoring</b>	High-resistance driver
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<b>Resolution, max.</b>	5000 S/R
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<b>Accuracy (in angular seconds)</b>	$\pm 18^\circ$ mech. $\times$ 3600/revolution z
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<b>Electr. speed, permissible</b>	$(18 \times 10^6)$ rpm/revolution
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<b>Mech. speed, max.</b>	12,000 rpm
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<b>Friction torque (at 20 °C (68 °F))</b>	$\leq 0.01$ Nm (0.08 lb <sub>f</sub> -in)
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<b>Starting torque (at 20 °C (68 °F))</b>	$\leq 0.01$ Nm (0.08 lb <sub>f</sub> -in)
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<b>Shaft loading capability</b>	
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- $n > 6000$  rpm
- Axial 10 N (2.2 lb<sub>f</sub>)
- Radial at shaft extension 20 N (4.5 lb<sub>f</sub>)
- $n \leq 6000$  rpm

<b>Product name</b>	<b>TTL (RS 422) incremental encoder</b>
<ul style="list-style-type: none"> <li>• Axial</li> </ul>	40 N (9 lbf)
<ul style="list-style-type: none"> <li>• Radial at shaft extension</li> </ul>	60 N (13.5 lbf)
<b>Angular acceleration, max.</b>	$> 10^5 \text{ rad/s}^2$
<b>Moment of inertia of rotor</b>	$1.45 \times 10^{-6} \text{ kgm}^2$ ( $12.83 \times 10^{-6} \text{ lbf-in-s}^2$ )
<b>Vibration (55 ... 2000 Hz) in accordance with EN 60068-2-6</b>	$\leq 300 \text{ m/s}^2$ (984 ft/s <sup>2</sup> )
<b>Shock in accordance with EN 60068-2-27</b>	
<ul style="list-style-type: none"> <li>• 2 ms</li> </ul>	$\leq 2000 \text{ m/s}^2$ (6563 ft/s <sup>2</sup> )
<ul style="list-style-type: none"> <li>• 6 ms</li> </ul>	$\leq 1000 \text{ m/s}^2$ (3281 ft/s <sup>2</sup> )
<b>Operating temperature</b>	
<ul style="list-style-type: none"> <li>• Flange socket or fixed cable</li> </ul>	
<ul style="list-style-type: none"> <li>• At <math>V_p = 5 \text{ V} \pm 10\%</math></li> </ul>	-40 ... +100 °C (-40 ... +212 °F)
<ul style="list-style-type: none"> <li>• At <math>V_p = 10 \dots 30 \text{ V}</math></li> </ul>	-40 ... +70 °C (-40 ... +158 °F)
<ul style="list-style-type: none"> <li>• Flexible cable</li> </ul>	
<ul style="list-style-type: none"> <li>• At <math>V_p = 5 \text{ V} \pm 10\%</math></li> </ul>	-10 ... +100 °C (+14 ... +212 °F)
<ul style="list-style-type: none"> <li>• At <math>V_p = 10 \dots 30 \text{ V}</math></li> </ul>	-10 ... +70 °C (+14 ... +158 °F)
<b>Degree of protection in accordance with EN 60529 (IEC 60529)</b>	
<ul style="list-style-type: none"> <li>• Without shaft input</li> </ul>	IP67
<ul style="list-style-type: none"> <li>• With shaft input</li> </ul>	IP64
<b>EMC</b>	Tested in accordance with the electromagnetic compatibility directive 89/336/EEC and the regulations of the EMC guidelines (applicable basic standards).
<b>Weight, approx.</b>	0.25 kg (0.55 lb)
<b>CE marking</b>	Yes

1) With recommended cable and input circuitry of the follow-up electronics, observe max. permissible cable length of module to be evaluated.

<b>Product name</b>	<b>TTL (RS 422) double-track incremental encoder</b>
<b>Encoder operating voltage</b>	5 V DC $\pm 5\%$
<b>Sampling frequency, max.</b>	
• Track 1	160 kHz
• Track 2	1 MHz
<b>No-load current consumption, max.</b>	
• Track 1	150 mA
• Track 2	150 mA
<b>Signal level</b>	TTL (RS 422)
<b>Outputs protected against short-circuit to 0 V</b>	Yes
<b>Switching time (10 ... 90%) (with 1 m (3.3 ft) cable and recommended input circuit)</b>	Rise/fall time $t_+/t_- \leq 100$ ns
<b>Phase angle, signal A to B min. edge spacing at:</b>	90°
• 1 MHz (track 2)	$\geq 0.125$ $\mu$ s
• 160 kHz (track 1)	$\geq 0.8$ $\mu$ s
<b>Cable length to electronic circuitry <sup>1)</sup>, max.</b>	
• Up to 500 kHz	100 m (328 ft)
• Up to 1 MHz	50 m (164 ft)
<b>Resolution, max.</b>	
• Track 1	1024 S/R
• Track 2	9000 S/R
<b>Accuracy (in angular seconds)</b>	
• Track 1	$\pm 63$
• Track 2	$\pm 12$
<b>Electr. speed, permissible</b>	
• Track 1	9000 rpm

<b>Product name</b>	<b>TTL (RS 422) double-track incremental encoder</b>
<ul style="list-style-type: none"> <li>Track 2</li> </ul>	6500 rpm
<b>Mech. speed, max.</b>	12,000 rpm
<b>Friction torque (at 20 °C (68 °F))</b>	≤ 0.01 Nm (0.08 lb <sub>f</sub> -in)
<b>Starting torque (at 20 °C (68 °F))</b>	≤ 0.01 Nm (0.08 lb <sub>f</sub> -in)
<b>Shaft loading capability</b>	
<ul style="list-style-type: none"> <li><math>n \leq 6000</math> rpm</li> <li>Axial</li> <li>Radial at shaft extension</li> </ul>	10 N(2.2 lb <sub>f</sub> ) 20 N (4.5 lb <sub>f</sub> )
<b>Angular acceleration, max.</b>	> 10 <sup>5</sup> rad/s <sup>2</sup>
<b>Moment of inertia of rotor</b>	20 × 10 <sup>-6</sup> kgm <sup>2</sup> (177 × 10 <sup>-6</sup> lb <sub>f</sub> -in-s <sup>2</sup> )
<b>Vibration (55 ... 2000 Hz) in accordance with EN 60068-2-6</b>	≤ 100 m/s <sup>2</sup> (328 ft/s <sup>2</sup> )
<b>Shock (6 ms) to EN 60068-2-27</b>	≤ 1000 m/s <sup>2</sup> (3281 ft/s <sup>2</sup> )
<b>Operating temperature</b>	-10 ... +70 °C (+14 ... +158 °F)
<b>Degree of protection in accordance with EN 60529 (IEC 60529)</b>	
<ul style="list-style-type: none"> <li>Without shaft input</li> <li>With shaft input</li> </ul>	IP67 IP64
<b>EMC</b>	Tested in accordance with the electromagnetic compatibility directive 89/336/EEC and the regulations of the EMC guidelines (applicable basic standards).
<b>Weight, approx.</b>	0.7 kg (1.5 lb)
<b>CE marking</b>	Yes

1) With recommended cable and input circuitry of the follow-up electronics, observe max. permissible cable length of module to be evaluated.