## Contactors for Switching Motors

## Technical specifications



## DC load

Rated operating current $I_{\mathrm{e}} / D C-12$
For rated operating voltage $U_{e}$

|  |  | 10 | 10 |
| :--- | :--- | :--- | :--- | :--- | :--- |


| Contactor | Type | 3TB50 to 3TB56 |
| :--- | :--- | :--- |
| CSA and UL rated data for the auxiliary contacts | AC V, | 600 |
| Rated voltage | max. |  |
| Switching capacity | A 600, P 600 |  |

1) Values in brackets apply to auxiliary contacts with offset NC contact.

## Contactors for Switching Motors

## Contactors with DC solenoid system

## 3-pole, 55 ... 200 kW

## Contact endurance of main contacts

The characteristics show the contact endurance of contactors when switching resistance and inductive AC loads (AC-1/AC-3) depending on the breaking current and rated operating voltage. It is assumed that the operating mechanisms are switched randomly, i.e. not synchronized with the phase angle of the supply system.

The rated operating current $I_{\mathrm{e}}$ complies with utilization category AC-4 (breaking of 6 times the rated operating current) and is intended for a contact endurance of about 200000 operating cycles.
If a shorter endurance is sufficient, the rated operating current $I_{\mathrm{e}} / \mathrm{AC}-4$ can be increased.

If the contacts are used for mixed operation i.e. if standard switching (breaking of the rated operating current in accordance with utilization category AC-3) is sometimes mixed with jog mode (breaking of multiples of the rated operating current in accordance with utilization category AC-4), the endurance of the contacts can be estimated with the following formula:

$$
x=\frac{A}{1+\frac{C}{100}\left(\frac{A}{B}-1\right)}
$$

The following abbreviations are used in the formula:
$X$ Contact endurance for mixed operation in operating cycles
A Contact endurance for normal operation ( $I_{\mathrm{a}}=I_{\mathrm{e}}$ ) in operating cycles
B Contact endurance for jog mode ( $I_{a}=$ multiples of $I_{\mathrm{e}}$ ) in operating cycles
C Number of jog operations of total operations in percent


3TB50 to 3TB56 contactors
Legend for the diagrams:
$P_{\mathrm{N}}=$ Rated output for squirrel-cage motors at 400 V
$I_{\mathrm{a}}=$ Breaking current
$I_{\mathrm{e}}=$ Rated operating current

Contactors for Switching Motors


- Opening delay ${ }^{3)}$
,

Load rating with AC
Utilization category AC-1, switching resistive loads

Rated operating current $I_{\mathrm{e}}$
at $40^{\circ} \mathrm{C}$ up to 690 V at $55^{\circ} \mathrm{C}$ up to 690 V

A
A
A
kW

Rated output power of AC loads 4)
p.f. $=0.95$ (for $55^{\circ} \mathrm{C}$ )

Minimum conductor cross-section for loads with $I_{\mathrm{e}}$

## Utilization category AC-2 and AC-3

Utilization category AC-4 (for $I_{\mathrm{a}}=6 \times I_{\mathrm{e}}$ )

- The following applies to contact endurances of about 200,000 operating cycles:
- Rated operating current $l_{e}$
- Rated output power for squirrelcage motors at 50 Hz and 60 Hz

Maximum permissible rated operat-
ing voltage $I_{\mathrm{e}} / \mathrm{AC}-4$

1) For reversing duty, deviations from the vertical axis are not permitted.
2) See Page $2 / 80$.
3) The opening delays can increase if the contactor coils are damped against voltage peaks.
4) Industrial furnaces and electric heaters with resistance heating, for example (increased power consumption on heating up has been taken into account).
5) See selection tables, Page $2 / 84$

## Contactors for Switching Motors

## Contactors with DC solenoid system

## 3 -pole, 55 ... 200 kW

| Contactor $\begin{array}{ll}\text { Type } \\ & \text { Size }\end{array}$ | Type Size |  | $\begin{aligned} & 3 \text { 3TB50 } \\ & 6 \end{aligned}$ | $\begin{aligned} & \text { 3TB52 } \\ & 8 \end{aligned}$ | $\begin{aligned} & 3 \text { TB54 } \\ & 10 \end{aligned}$ | $\begin{aligned} & \text { 3TB56 } \\ & 12 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Main circuit |  |  |  |  |  |  |
| Load rating with AC |  |  |  |  |  |  |
| Switching of low-inductance (low-loss, metallized dielectric) AC capacitors ${ }^{1)}$ |  |  |  |  |  |  |
| Rated operating current $I_{\mathrm{e}}$ at 400 V |  | A | 87 | 144 | 217 | 289 |
| Rated output power of single capacitors at 50 Hz | $\begin{aligned} & 230 \mathrm{~V} \\ & 400 \mathrm{~V} \\ & 500 \mathrm{~V} \\ & 690 \mathrm{~V} \end{aligned}$ | kvar <br> kvar <br> kvar <br> kvar | $\begin{aligned} & 35 \\ & 60 \\ & 80 \\ & 60 \end{aligned}$ | $\begin{aligned} & 58 \\ & 100 \\ & 130 \\ & 100 \end{aligned}$ | $\begin{aligned} & 87 \\ & 150 \\ & 190 \\ & 150 \end{aligned}$ | $\begin{aligned} & 115 \\ & 200 \\ & 265 \\ & 200 \end{aligned}$ |
| Rated output power of bank of capacitors (minimum inductance between $6 \mu \mathrm{H}$ connected in parallel capacitors) at 50 Hz | $\begin{aligned} & 230 \mathrm{~V} \\ & 400 \mathrm{~V} \\ & 500 \mathrm{~V} \\ & 690 \mathrm{~V} \end{aligned}$ | kvar <br> kvar <br> kvar <br> kvar | $\begin{aligned} & 30 \\ & 50 \\ & 66 \\ & 50 \end{aligned}$ | $\begin{aligned} & 40 \\ & 70 \\ & 90 \\ & 70 \end{aligned}$ | $\begin{aligned} & 66 \\ & 115 \\ & 145 \\ & 115 \end{aligned}$ | $\begin{aligned} & 85 \\ & 150 \\ & 195 \\ & 150 \end{aligned}$ |

Load rating with DC
Utilization category DC-1
Switching of resistive load ( $\mathrm{L} / \mathrm{R} \leq 1 \mathrm{~ms}$ )
Rated operating current $I_{\mathrm{e}}$ (for $55^{\circ} \mathrm{C}$ )

paths

- 3 series-connected conducting paths

| 24 V | A | 160 | 200 | 300 | 400 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 60 V | A | 80 | 80 | 300 | 330 |
| 110 V | A | 18 | 18 | 33 | 33 |
| 220 V | A | 3.4 | 3.4 | 3.8 | 3.8 |
| 440 V | A | 0.8 | 0.8 | 0.9 | 0.9 |
| 600 V | A | 0.5 | 0.5 | 0.6 | 0.6 |
| 24 V | A | 160 | 200 | 300 | 400 |
| 60 V | A | 160 | 200 | 300 | 400 |
| 110 V | A | 160 | 200 | 300 | 400 |
| 220 V | A | 20 | 20 | 300 | 400 |
| 440 V | A | 3.2 | 3.2 | 4 | 4 |
| 600 V | A | 1.6 | 1.6 | 2 | 2 |
| 24 V | A | 160 | 200 | 300 | 400 |
| 60 V | A | 160 | 200 | 300 | 400 |
| 110 V | A | 160 | 200 | 300 | 400 |
| 220 V | A | 160 | 200 | 300 | 400 |
| 440 V | A | 11.5 | 11.5 | 11 | 11 |
| 600 V | A | 4 | 4 | 5.2 | 5.2 |

Utilization category DC-3 and DC-5
Shunt-wound and series-wound motors ( $\mathrm{L} / \mathrm{R} \leq 15 \mathrm{~ms}$ ) Rated operating current $I_{\mathrm{e}}$ (for $55^{\circ} \mathrm{C}$ )

- 1 conducting path
- 2 conducting paths in series
- 3 series-connected conducting paths

| 24 V | A | 16 | 16 | 35 | 35 |
| ---: | :--- | :--- | :--- | :--- | :--- |
| 60 V | A | 7.5 | 7.5 | 11 | 11 |
| 110 V | A | 2.5 | 2.5 | 3 | 3 |
| 220 V | A | 0.6 | 0.6 | 0.6 | 0.6 |
| 440 V | A | 0.17 | 0.17 | 0.18 | 0.18 |
| 600 V | A | 0.12 | 0.12 | 0.125 | 0.125 |
| 24 V | A | 160 | 200 | 300 | 400 |
| 60 V | A | 160 | 200 | 300 | 400 |
| 110 V | A | 160 | 200 | 300 | 400 |
| 220 A | A | 2.5 | 2.5 | 2.5 | 2.5 |
| 440 V | A | 0.65 | 0.65 | 0.65 | 0.65 |
| 600 V | A | 0.37 | 0.37 | 0.37 | 0.37 |
| 24 V | A | 160 | 200 | 300 | 400 |
|  |  |  |  |  |  |
| 60 V | A | 160 | 200 | 300 | 400 |
| 110 V | A | 160 | 200 | 300 | 400 |
| 220 V | A | 160 | 200 | 300 | 400 |
| 440 V | A | 1.4 | 1.4 | 1.4 | 1.4 |
| 600 V | A | 0.75 |  | 0.75 | 0.75 |

Operating frequency
Operating frequency $\boldsymbol{z}$ in operating cycles/hour

- Contactors without overload relay
- Contactors with overload relay (mean value)

| AC-1 | $h^{-1}$ | 1000 |
| :--- | :--- | :--- |
| AC-2 | $h^{-1}$ | 500 |
| AC-3 | $h^{-1}$ | 500 |
| AC-4 | $h^{-1}$ | 250 |
|  | $h^{-1}$ | 15 |

1) Contact lifetime 0.1 million operating cycles.

| Contactor | Type Size |  | 3TB50 | $\begin{aligned} & 3 \text { TB52 } \\ & 8 \end{aligned}$ | $\begin{aligned} & \text { 3TB54 } \\ & 10 \end{aligned}$ | $\begin{aligned} & \text { 3TB56 } \\ & 12 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Conductor cross-sections |  |  |  |  |  |  |
| Screw terminals | Main conductors <br> - Finely stranded with cable lug $\mathrm{mm}^{2}$ <br> - Stranded with cable lug $\mathrm{mm}^{2}$ <br> - Busbars <br> - Terminal screw |  | $\begin{aligned} & 16 \ldots 70 \\ & 25 \ldots 70 \\ & 15 \times 3 \\ & M 6 \end{aligned}$ | $\begin{aligned} & 35 \ldots 95 \\ & 50 \ldots 120 \\ & 20 \times 3 \\ & \text { M } 8 \end{aligned}$ | $\begin{aligned} & 50 \ldots 240 \\ & 70 \ldots 240 \\ & 25 \times 5 \\ & \text { M } 10 \end{aligned}$ | $\begin{aligned} & 50 \ldots 240 \\ & 70 \ldots 240 \\ & 2 \times(25 \times 3) \\ & \text { M } 10 \end{aligned}$ |
|  | Auxiliary conductors <br> - Solid <br> - Finely stranded with end sleeve <br> - Pin-end connector (DIN 46231) | $\begin{aligned} & \mathrm{mm}^{2} \\ & \mathrm{~mm}^{2} \\ & \mathrm{~mm}^{2} \end{aligned}$ | $\begin{aligned} & 1 \ldots .2 .5 \\ & 0.75 \ldots 1.5 \\ & 2 \times 1 \ldots 2.5 \end{aligned}$ |  |  |  |
|  | Protective conductor: <br> - Stranded with cable lug | $\mathrm{mm}^{2}$ | - | $25 . .70$ | $35 \ldots 70$ | $50 \ldots 120$ |
| CSA and UL rated data |  |  |  |  |  |  |
| CSA rated data |  |  |  |  |  |  |
| Continuous current | Open Enclosed | $\begin{aligned} & \text { A } \\ & \text { A } \end{aligned}$ | $\begin{aligned} & 150 \\ & 135 \end{aligned}$ | $\begin{aligned} & 170 \\ & 153 \end{aligned}$ | $\begin{aligned} & 240 \\ & 215 \end{aligned}$ | $\begin{aligned} & 300 \\ & 270 \end{aligned}$ |
| Rated output power for induction motors at 60 Hz (enclosed) | $\begin{aligned} & 115 \mathrm{~V} \\ & 230 \mathrm{~V} \\ & 460 \mathrm{~V} \\ & 575 \mathrm{~V} \end{aligned}$ | hp hp hp hp | $\begin{aligned} & 25 \\ & 50 \\ & 100 \\ & 125 \end{aligned}$ | $\begin{aligned} & 30 \\ & 60 \\ & 120 \\ & 160 \end{aligned}$ | $\begin{aligned} & 40 \\ & 75 \\ & 150 \\ & 200 \end{aligned}$ | $\begin{aligned} & 50 \\ & 100 \\ & 200 \\ & 250 \end{aligned}$ |
| Overload relay | Type Adjustment range | A | $\begin{aligned} & 3 \text { RB1056 } \\ & 50 \ldots 200 \end{aligned}$ | $\begin{aligned} & 3 R B 1056 \\ & 50 \ldots 200 \end{aligned}$ | $\begin{aligned} & 3 R B 1066 \\ & 50 \ldots 250 \end{aligned}$ | $\begin{aligned} & 3 R B 1066 \\ & 200 \ldots 540 \end{aligned}$ |
| NEMA/EEMAC size | Contactors <br> Starter (= contactors + overload <br> relay, enclosed) |  | $\begin{aligned} & 4 \\ & 3 \end{aligned}$ | $\begin{aligned} & 4 \\ & 4 \end{aligned}$ | $\begin{aligned} & 4 \\ & 4 \end{aligned}$ | $\begin{aligned} & 5 \\ & 5 \end{aligned}$ |
| UL rated data |  |  |  |  |  |  |
| Continuous current | Open Enclosed | $\begin{aligned} & \text { A } \\ & \text { A } \end{aligned}$ | $\begin{aligned} & 150 \\ & 135 \end{aligned}$ | $\begin{aligned} & 150 \\ & 135 \end{aligned}$ | $\begin{aligned} & 240 \\ & 215 \end{aligned}$ | $\begin{aligned} & 390 \\ & 350 \end{aligned}$ |
| Rated output power for induction motors at 60 Hz | $\begin{aligned} & 115 \mathrm{~V} \\ & 230 \mathrm{~V} \\ & 460 \mathrm{~V} \\ & 575 \mathrm{~V} \end{aligned}$ | hp hp hp hp | $\begin{aligned} & 25 \\ & 50 \\ & 100 \\ & 125 \end{aligned}$ | $\begin{aligned} & 25 \\ & 50 \\ & 100 \\ & 125 \end{aligned}$ | $\begin{aligned} & 30 \\ & 75 \\ & 150 \\ & 200 \end{aligned}$ | $\begin{aligned} & 125 \\ & 250 \\ & 300^{1} \end{aligned}$ |
| Overload relay | Type Adjustment range |  | $\begin{aligned} & 3 R B 1056 \\ & 50 \ldots 200 \end{aligned}$ | $\begin{aligned} & 3 R B 1056 \\ & 50 \ldots 200 \end{aligned}$ | $\begin{aligned} & 3 R B 1066 \\ & 50 \ldots 250 \end{aligned}$ | $\begin{aligned} & \text { 3RB1066 } \\ & 200 \ldots 540 \end{aligned}$ |
| NEMA/EEMAC size | Contactors <br> Starter (= contactors + overload <br> relay, enclosed) |  | $\begin{aligned} & 4 \\ & 3 \end{aligned}$ | $\begin{aligned} & 4 \\ & 4 \end{aligned}$ | $\begin{aligned} & 4 \\ & 4 \end{aligned}$ | $\begin{aligned} & 5 \\ & 5 \end{aligned}$ |
| Short-circuit protection devices |  |  |  |  |  |  |
| - Fuse CLASS RK5 |  | A | 400 | 400 | 450 | 600 |
| - Power switch to UL 489 |  | A | 175 | 175 | 250 | 600 |

1) At AC 575/AC 600 V .
